

ABSTRACT OF DISCLOSURE

A robot hand apparatus (1) includes four of finger mechanisms (20) each elongates from a base(10), a motor (30) 5 actuating each finger mechanism (20), four of rotation rollers (50) each connects with corresponding finger mechanism (20) for actuating each finger mechanism (20), and a power transmission mechanism (60) transmitting a power from the motor (30) to each rotation roller (50) at different timing.

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